

## Partial Fraction Decomposition of Matrices and Parallel Computing

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**Abstract.** We are interested in the design of parallel numerical schemes for linear systems. We give an effective solution to this problem in the following case: the matrix  $A$  of the linear system is the product of  $p$  nonsingular matrices  $A_i^m$  with specific shape:  $A_i = I - h_i X$  for a fixed matrix  $X$  and real numbers  $h_i$ . Although having a special form, these matrices  $A_i$  arise frequently in the discretization of evolutionary Partial Differential Equations. For example, one step of the implicit Euler scheme for the evolution equation  $u' = Xu$  reads  $(I - hX)u^{n+1} = u^n$ . Iterating  $m$  times such a scheme leads to a linear system  $Au^{n+m} = u^n$ . The idea is to express  $A^{-1}$  as a linear combination of elementary matrices  $A_i^{-1}$  (or more generally in term of matrices  $A_i^{-k}$ ). Hence the solution of the linear system with matrix  $A$  is a linear combination of the solutions of linear systems with matrices  $A_i$  (or  $A_i^k$ ). These systems are then solved simultaneously on different processors.

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### 1 Introduction

Let  $X$  be a real  $n \times n$  square real (or complex) matrix and  $(h_i)_{i=1}^p$  a collection of pairwise distinct real numbers. Matrices of the shape

$$A_i = I - h_i X \quad (1.1)$$

with  $I$  the  $n \times n$  identity matrix, appear in many numerical schemes for differential equations. For small  $h_i$  (discretization parameters), such matrices are nonsingular. So is matrix

$$A = \prod_{i=1}^p A_i^m \quad (1.2)$$

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for any  $m \in \mathbb{N}$ . Note that matrices  $A_i$  commute and  $A$  is a polynomial of the single variable  $X$ . The problem of interest here is the following: given  $y \in \mathbb{R}^n$ , compute the unique solution  $x \in \mathbb{R}^n$  of the linear system

$$Ax = b \tag{1.3}$$

using several processors at our disposal. The aim is to use parallel computing to save computational time. The key idea consists in expressing matrix  $A^{-1}$  as a linear combination of matrices  $((A_i^{-k})_{i=1}^p)_{k=1}^m$ . Since matrices  $A_i$  we consider come from the discretization of differential equations by time implicit scheme, our method falls into the family of "parallelization in time" algorithms. More precisely, it is a Direct Parallel Time Integration like the one developed by Y. Maday and E. Rønquist in [5], based on tensor-product space-time solvers. We refer to the survey article by M. Gander [1] for a comprehensive overview of parallel time integration methods.

Our method is also related to exponential integrators. Consider the linear constant-coefficients system  $u_t = Lu$  whose solution is  $u(t) = e^{tL}u_0$ . Applying  $p$  steps of an implicit scheme, we obtain a numerical evolution  $u_p$  defined by  $Au_p = u_0$  with  $A$  the product of  $p$  matrices  $A_i$  (see Section 2). Writing  $A^{-1}$  as a linear combination of  $A_i^{-1}$ 's is equivalent to seek for a rational approximation of the solution operator  $e^{tL}$ . Rational approximation of the exponential is an important problem in numerical analysis. Consult the survey paper by M. Hochbruck and A. Ostermann ([3]) on exponential integrators.

The paper is organised as follows.

- In Section 2, we present the algebraic problem to be solved.
- In Section 3, we explain how the method can be used to solve homogeneous evolution equations  $u_t = \mathcal{L}u$ .
- In Section 4, we consider nonhomogeneous evolution equations  $u_t = \mathcal{L}u + f$  and derive a new parallel algorithm to solve such problems.
- The last section contains remarks on the reliability of the method and its limitations.

All computations have been done using FreeFem++, a Finite Elements software for the discretization of Partial Differential Equations [2].

## 2 The algebraic problem

We consider in this section the homogeneous linear time-evolution problem

$$\mathbf{u}_t = \mathcal{L}\mathbf{u}. \tag{2.1}$$

Section 4 is devoted the nonhomogeneous case which requires a different numerical treatment. Starting from an initial data  $\mathbf{u}^0$ , the time discretization of this equation by implicit