

## IMPROVED ERROR ESTIMATES FOR MIXED FINITE ELEMENT FOR NONLINEAR HYPERBOLIC EQUATIONS: THE CONTINUOUS-TIME CASE<sup>\*1)</sup>

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### Abstract

Improved  $L^2$ -error estimates are computed for mixed finite element methods for second order nonlinear hyperbolic equations. Results are given for the continuous-time case. The convergence of the values for both the scalar function and the flux is demonstrated. The technique used here covers the lowest-order Raviart-Thomas spaces, as well as the higher-order spaces. A second paper will present the analysis of a fully discrete scheme (Numer. Math. J. Chinese Univ. vol.9, no.2, 2000, 181-192).

*Key words:* Nonlinear hyperbolic equations, Mixed finite element methods, Error estimates, Superconvergence.

### 1. Introduction

Let  $\Omega$  be a bounded domain in  $\mathbf{R}^2$  with Lipschitz boundary  $\partial\Omega$ , and unit outward normal  $\nu$ . For fixed  $0 < T < \infty$ ,  $J = (0, T]$ , we discuss mixed finite element approximations of second order nonlinear hyperbolic equation

$$c(x, u)u_{tt} - \nabla \cdot (a(x, u)\nabla u) = f(x, u, t), \quad x \in \Omega, \quad t \in J, \quad (1.1)$$

with initial conditions

$$u(x, 0) = u_0(x), \quad u_t(x, 0) = u_1(x), \quad x \in \Omega, \quad (1.2)$$

and Dirichlet boundary condition

$$u(x, t) = -g(x, t), \quad (x, t) \in \partial\Omega \times J. \quad (1.3)$$

We shall assume that the functions  $c(x, u)$ ,  $a(x, u)$ ,  $f(x, u, t)$ ,  $g(x, t)$  and solution  $u(x, t)$  have sufficient regularity. Additionally, we assume that there exist constants  $c_*$ ,  $c^*$ ,  $a_*$ , and  $a^*$  such that

$$0 < c_* \leq c(x, u) \leq c^*, \quad 0 < a_* \leq a(x, u) \leq a^*, \quad (1.4)$$

Optimal rates of convergence for Galerkin approximations to a class of second order nonlinear hyperbolic equations have been previously derived by Yuan yi-rang and Wang hong [9, 12-13]. The study of superconvergence for the gradient of the solution of second order hyperbolic equation was provided in [1, 6, 10-11]. Recently, several works have been devoted to the analysis of the mixed finite element methods (see [2-5, 8]). Cowsar, Dupont, Wheeler [2] have considered the convergence of the mixed finite element methods for second order linear hyperbolic equation.

In this paper, we formulate a mixed finite element scheme for the approximation of (1.1)-(1.3) and establish the superconvergence  $L^2$ -estimate between the finite element solution and its elliptic projection. The method here gives a direct approximation of the flux, rather than

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one that requires differentiation and multiplication by a possibly rapidly varying coefficient; so, the direct evaluation of the flux can be expected to give improved accuracy for the same computational effort.

### 2. Mixed Finite Element Formulation for Nonlinear Hyperbolic Problem

Let  $V = H(\text{div}; \Omega)$ ,  $W = L^2(\Omega)$ . Introduce the flux variable  $z$ :

$$z = -a(x, u)\nabla u, \tag{2.1}$$

and let  $\alpha(u) = \alpha(x, u) = 1/a(x, u)$ ,  $c(u) = c(x, u)$ ,  $f(u) = f(x, u, t)$ . Before defining a mixed finite element procedure we rewrite (1.1)-(1.3) in the following weak formulation

$$(u(0), w) = (u_0, w), \quad w \in W, \tag{2.2}$$

$$(u_t(0), w) = (u_1, w), \quad w \in W, \tag{2.3}$$

$$(c(u)u_{tt}, w) + (\nabla \cdot z, w) = (f(u), w), \quad w \in W, \tag{2.4}$$

$$(\alpha(u)z, v) - (\nabla \cdot v, u) = \langle g, v \cdot \nu \rangle, \quad v \in V, \tag{2.5}$$

where  $(\cdot, \cdot)$  is  $L^2(\Omega)$  inner product,  $\langle \cdot, \cdot \rangle$  is the  $L^2(\partial\Omega)$  inner product.

For  $h$  a small positive parameter we take  $W_h \times V_h \subset W \times V$  to be the Raviart-Thomas space [8] of index  $k$ , where  $k$  is fixed nonnegative integer, associated with  $\mathcal{T}_h$ .

The continuous-time mixed finite element approximation to (2.2)-(2.5) is defined as a map from  $[0, T]$  into  $W_h \times V_h$  given by the pair  $(U(\cdot, t), Z(\cdot, t))$  satisfying

$$(c(U)U_{tt}, w) + (\nabla \cdot Z, w) = (f(U), w), \quad w \in W_h, \tag{2.6}$$

$$(\alpha(U)Z, v) - (\nabla \cdot v, U) = \langle g, v \cdot \nu \rangle, \quad v \in V_h, \tag{2.7}$$

with initial conditions

$$U(0) = \tilde{U}(0), \quad U_t(0) = \tilde{U}_t(0), \quad Z(0) = \tilde{Z}(0), \tag{2.8}$$

where  $(\tilde{U}(\cdot, t), \tilde{Z}(\cdot, t))$  is the elliptic mixed method projection to be defined later.

### 3. Mixed Method Projection

For the solution  $u(x, t)$ , let  $\alpha_1 = \alpha(u)$ ,  $\gamma(u) = \alpha_u(u)z$ ,  $\alpha_u(u) = \frac{\partial \alpha(u)}{\partial u}$ , and  $\gamma_1 = \gamma(u)$ . Define a linear mixed elliptic projection of  $W \times V$  onto  $W_h \times V_h$  by the  $(u, z) \rightarrow (\tilde{U}, \tilde{Z})$  determined by the relations

$$\begin{aligned} (\nabla \cdot (z - \tilde{Z}), w) + \lambda(u - \tilde{U}, w) &= 0, & w \in W_h, \\ (\alpha_1(z - \tilde{Z}), v) - (\nabla \cdot v, u - \tilde{U}) + (\gamma_1(u - \tilde{U}), v) &= 0, & v \in V_h, \end{aligned} \tag{3.1}$$

for each  $t \in J$ . The positive constant  $\lambda$  will be assumed to be a sufficiently large constant such that

$$(\alpha_1 \zeta, \zeta) + \lambda(\xi, \xi) + (\gamma_1 \xi, \zeta) \geq \lambda_0 (\|\zeta\|_0^2 + \|\xi\|_0^2), \quad \text{for } \zeta \in V \text{ and } \xi \in W, \tag{3.2}$$

where  $\lambda_0 > 0$  is independent of  $t \in J$ . Let

$$\begin{aligned} \eta &= u - \tilde{U}, & \rho &= z - \tilde{Z}, \\ \xi &= \tilde{U} - U, & \zeta &= \tilde{Z} - Z. \end{aligned} \tag{3.3}$$

As shown in [3, 4, 8], there exist the Raviart-Thomas projection  $\Pi_h : V \rightarrow V_h$  and  $L^2$ -projection  $P_h : W \rightarrow W_h$  such that for  $0 < q \leq \infty$ ,

$$\text{div} \circ \Pi_h = P_h \circ \text{div}, \tag{3.4}$$