

Unique Common Fixed Points for Two Weakly C^* -contractive Mappings on Partially Ordered 2-metric Spaces

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Abstract: In this paper, we give existence theorems of common fixed points for two mappings with a weakly C^* -contractive condition on partially ordered 2-metric spaces and give a sufficient condition under which there exists a unique common fixed point.

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1 Introduction and Preliminaries

Gähler^{[1]–[3]} introduced the definition of 2-metric spaces and discussed the existence problems of fixed points. From then on, many authors discussed and obtained the existence problems of coincidence points and (common) fixed points with a variety of different forms. Especially, there have appeared a lot of useful results in recent years, see the references [4]–[16] and the related papers. All these results generalize and improve the corresponding fixed point theorem in metric spaces.

Definition 1.1^{[1]–[3]} A 2-metric space (X, d) consists of a nonempty set X and a function $d: X \times X \times X \rightarrow [0, +\infty)$ such that

- (i) for distant elements $x, y \in X$, there exists a $u \in X$ such that $d(x, y, u) \neq 0$;
- (ii) $d(x, y, z) = 0$ if and only if at least two elements in $\{x, y, z\}$ are equal;
- (iii) $d(x, y, z) = d(u, v, w)$, where $\{u, v, w\}$ is any permutation of $\{x, y, z\}$;
- (iv) $d(x, y, z) \leq d(x, y, u) + d(x, u, z) + d(u, y, z)$ for all $x, y, z, u \in X$.

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Definition 1.2^{[1]–[3]} A sequence $\{x_n\}_{n \in \mathbf{N}_+}$ in 2-metric space (X, d) is said to be a Cauchy sequence if for each $\varepsilon > 0$ there exists a positive integer $N \in \mathbf{N}_+$ such that $d(x_n, x_m, a) < \varepsilon$ for all $a \in X$ and $n, m > N$. A sequence $\{x_n\}_{n \in \mathbf{N}_+}$ is said to be convergent to $x \in X$ if for each $a \in X$, $\lim_{n \rightarrow +\infty} d(x_n, x, a) = 0$. And we write that $x_n \rightarrow x$ and call x the limit of $\{x_n\}_{n \in \mathbf{N}_+}$. A 2-metric space (X, d) is said to be complete if every Cauchy sequence in X is convergent.

Choudhury^[17] introduced the next definition in a real metric space:

Definition 1.3^[17] Let (X, d) be a metric space and $T: X \rightarrow X$ be a map. T is said to be weak C -contraction if there exists a continuous function $\varphi: [0, +\infty)^2 \rightarrow [0, +\infty)$ with $\varphi(s, t) = 0 \iff s = t = 0$ such that

$$d(Tx, Ty) \leq \frac{1}{2}[d(x, Ty) + d(y, Tx)] - \varphi(d(x, Ty), d(y, Tx)), \quad x, y \in X.$$

Choudhury^[17] also proved that any map satisfying the weak C -contraction has a unique fixed point on a complete metric space (see [17], Theorem 2.1). Later, the above result was extended to the case in a complete ordered metric spaces (see [18], Theorems 2.1, 2.3 and 3.1).

In 2013, Definition 1.3 was extended to the case in a 2-metric space by Dung and Hang^[10] as follows:

Definition 1.4^[10] Let (X, \preceq, d) be an ordered 2-metric space, $T: X \rightarrow X$ a map. T is said to be weak C -contraction if there exists a continuous function $\varphi: [0, +\infty)^2 \rightarrow [0, +\infty)$ with $\varphi(s, t) = 0 \iff s = t = 0$ such that for any $x, y, a \in X$ with $x \preceq y$ or $y \preceq x$,

$$d(Tx, Ty, a) \leq \frac{1}{2}[d(x, Ty, a) + d(y, Tx, a)] - \varphi(d(x, Ty, a), d(y, Tx, a)).$$

Dung and Hang^[10] proved that any weakly C -contractive map has fixed points on complete ordered 2-metric spaces (see [10], Theorems 2.3, 2.4 and 2.5). The results generalized and improved the corresponding conclusions in [17]–[18].

Definition 1.5 Let (X, \preceq, d) be an ordered 2-metric space and $S, T: X \rightarrow X$ be two maps. S, T are said to be weakly C^* -contractive maps if there exists a continuous function $\varphi: [0, +\infty)^2 \rightarrow [0, +\infty)$ with $\varphi(s, t) = 0 \iff s = t = 0$ such that for any $x, y, a \in X$ with $x \preceq y$ or $y \preceq x$,

$$d(Sx, Ty, a) \leq kd(x, y, a) + l[d(x, Ty, a) + d(y, Sx, a)] - \varphi(d(x, Ty, a), d(y, Sx, a)),$$

where k and l are two real numbers satisfying $l > 0$ and $0 < k + l \leq 1 - l$.

Obviously, if $S = T$ and $k = 0$ and $l = \frac{1}{2}$, then Definition 1.5 becomes Definition 1.3.

Definition 1.6^[10] Let (X, d) be a 2-metric space and $a, b \in X$, $r > 0$. The set

$$B(a, b; r) = \{x \in X : d(a, b, x) < r\}$$

is said to be a 2-ball with centers a and b and radius r . Each 2-metric d on X generalizes a topology τ on X whose base is the family of 2-balls. τ is said to be a 2-metric topology.