

H^1 -Estimates of the Littlewood-Paley and Lusin Functions for Jacobi Analysis II

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Abstract. Let $(\mathbb{R}_+, *, \Delta)$ be the Jacobi hypergroup. We introduce analogues of the Littlewood-Paley g function and the Lusin area function for the Jacobi hypergroup and consider their (H^1, L^1) boundedness. Although the g operator for $(\mathbb{R}_+, *, \Delta)$ possesses better property than the classical g operator, the Lusin area operator has an obstacle arisen from a second convolution. Hence, in order to obtain the (H^1, L^1) estimate for the Lusin area operator, a slight modification in its form is required.

Key Words: Jacobi analysis, Jacobi hypergroup, g function, area function, real Hardy space.

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1 Introduction

One of main subjects of the so-called real method in classical harmonic analysis related to the Poisson integral $f * p_t$ is to investigate the Littlewood-Paley theory. For example, in the one dimensional setting, the following singular integral operators were respectively well-known as the Littlewood-Paley g function and the Lusin area function

$$g^{\mathbb{R}}(f)(x) = \left(\int_0^\infty \left| f * t \frac{\partial}{\partial t} p_t(x) \right|^2 \frac{dt}{t} \right)^{1/2}, \quad (1.1a)$$

$$S^{\mathbb{R}}(f)(x) = \left(\int_0^\infty \frac{1}{t} \chi_t * \left| f * t \frac{\partial}{\partial t} p_t \right|^2(x) \frac{dt}{t} \right)^{1/2}, \quad (1.1b)$$

where χ_t is the characteristic function of $[-t, t]$. These operators satisfy the maximal theorem, that is, a weak type L^1 estimate and a strong type L^p estimate for $1 < p \leq \infty$. Moreover, they are bounded from H^1 into L^1 (cf. [10–12]). Our matter of concern is to extend these results to other topological spaces X . Roughly speaking, in some examples of X of homogeneous type (see [2]), Poisson integrals are generalized on X and analogous

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Littlewood-Paley theory has been developed (cf. [2,5,10]). On the other hand, if the space X is not of homogeneous type, we encounter difficulties. As an example of X of non homogeneous type with Poisson integrals, noncompact Riemannian symmetric spaces $X = G/K$ are well-known. Lohoue [9] and Anker [1] generalize the Littlewood-Paley g function and the Luzin area function to G/K and show that they satisfy the maximal theorem (see below). However, we know little or nothing whether they are bounded from H^1 into L^1 , because we first have to find out a suitable definition of a real Hardy space on G/K . The aim of this paper is to introduce a real Hardy space $H^1(\Delta)$ and show that they are bounded from $H^1(\Delta)$ into $L^1(\Delta)$ for the Jacobi hypergroup $(\mathbb{R}_+, *, \Delta)$, which is a generalization of K -invariant setting on G/K of real rank one.

We briefly overview the Jacobi hypergroup $(\mathbb{R}_+, *, \Delta)$. We refer to [4] and [8] for a description of general context. For $\alpha \geq \beta \geq -\frac{1}{2}$ and $(\alpha, \beta) \neq (-\frac{1}{2}, -\frac{1}{2})$ we define the weight function Δ on \mathbb{R}_+ as

$$\Delta(x) = (2\operatorname{sh}x)^{2\alpha+1} (2\operatorname{ch}x)^{2\beta+1}.$$

Clearly, it follows that

$$\Delta(x) \leq c \begin{cases} e^{2\rho x}, & x > 1, \\ x^{2\gamma_0}, & x \leq 1, \end{cases}$$

where $\rho = \alpha + \beta + 1$ and $\gamma_0 = \alpha + \frac{1}{2}$. For $\lambda \in \mathbb{C}$ let ϕ_λ be the Jacobi function on \mathbb{R}_+ defined by

$$\phi_\lambda(x) = {}_2F_1\left(\frac{\rho+i\lambda}{2}, \frac{\rho-i\lambda}{2}; \alpha+1; -(\operatorname{sh}x)^2\right),$$

where ${}_2F_1$ the hypergeometric function. Then the Jacobi transform \hat{f} of a function f on \mathbb{R}_+ is defined by

$$\hat{f}(\lambda) = \frac{1}{\sqrt{2\pi}} \int_0^\infty f(x) \phi_\lambda(x) \Delta(x) dx.$$

We define a generalized translation on \mathbb{R}_+ by using the kernel form of the product formula of Jacobi functions: For $x, y \in \mathbb{R}_+$,

$$\phi_\lambda(x) \phi_\lambda(y) = \int_0^\infty \phi_\lambda(z) K(x, y, z) \Delta(z) dz.$$

The kernel $K(x, y, z)$ is non-negative and symmetric in the three variables. Then the generalized translation T_x of f is defined as

$$T_x f(y) = \int_0^\infty f(z) K(x, y, z) \Delta(z) dz$$

and the convolution of f, g is given by

$$f * g(x) = \int_0^\infty f(y) T_x g(y) \Delta(y) dy.$$