

Chebyshev Spectral-Finite Element Method for Two-Dimensional Unsteady Navier-Stokes Equation^{*1)}

Ben-yu Guo

(School of Mathematical Sciences, Shanghai Normal University, Shanghai 200234, China)

Song-nian He

(Department of Foundamental Sciences, Aircraft College of China, Tianjin 300300, China)

He-ping Ma

(Department of Mathematics, Shanghai University, Shanghai 201800, China)

Abstract

A mixed Chebyshev spectral-finite element method is proposed for solving two-dimensional unsteady Navier-Stokes equation. The generalized stability and convergence are proved. The numerical results show the advantages of this method.

Key words: Navier-Stokes equation, Chebyshev spectral-finite element method.

1. Introduction

Spectral method has been used successfully in computational fluid dynamics. For semi-periodic problems, we can use mixed Fourier-Chebyshev spectral method, Fourier spectral-finite difference method and Fourier spectral-finite element method (see[1–5]). As we know, many problems are fully non-periodic. But the sections of domains might be rectangular in certain directions. For example, the fluid flow in a cylindrical container. So we proposed Chebyshev spectral-finite element method(see[6]). In this paper, we develop mixed Chebyshev spectral-finite element method for two-dimensional unsteady Navier-Stokes equation.

2. The Scheme

Let $I_x = \{x / -1 < x < 1\}$, $I_y = \{y / 0 < y < 1\}$ and $\Omega = I_x \times I_y$ with the boundary $\partial\Omega$. The speed vector and the pressure are denoted by $U = (U_1, U_2)$ and P respectively. $\nu > 0$ is the kinetic viscosity. $U_0(x, y)$ and $f(x, y, t)$ are given functions. Let $T > 0$, $\partial_t = \frac{\partial}{\partial t}$, $\partial_x = \frac{\partial}{\partial x}$, and $\partial_y = \frac{\partial}{\partial y}$. The Navier-Stokes equation is as follows

$$\begin{cases} \partial_t U + \partial_x(U_1 U) + \partial_y(U_2 U) + \nabla P - \nu \nabla^2 U = f, & \text{in } \Omega \times (0, T], \\ \nabla^2 P + \Phi(U) = \nabla \cdot f, & \text{in } \Omega \times (0, T], \\ U|_{t=0} = U_0, & \text{in } \Omega \cup \partial\Omega \end{cases} \quad (2.1)$$

where

$$\Phi(U) = 2(\partial_y U_1 \partial_x U_2 - \partial_x U_1 \partial_y U_2).$$

Suppose that the boundary is a non-slip wall and so $U = 0$ on $\partial\Omega$. There is no boundary condition for the pressure. But if we use the second equation of (2.1) to evaluate the pressure,

* Received September 29, 1999.

¹⁾The work of this author is partially supported by the Chinese State Key Project of Basic Research N.G1999032804 and the Shanghai Natural Science Foundation N.00JC14057.

then we need a non-standard boundary condition. We assume approximately that $\frac{\partial P}{\partial n} = 0$ on $\partial\Omega$. For fixing the value of pressure, we require that

$$\mu(P, t) \equiv \int \int_{\Omega} P(x, y, t) \, dx dy = 0, \quad \forall t \in [0, T].$$

Clearly for each time t and U , the second equation of (2.1) is a Neumann problem for P . It can be verified that $\mu(\nabla \cdot f - \Phi(U), t) \equiv 0$ and so this problem is consistent (see [7]). The main advantage of this model is that the derivation of the second formula of (2.1) implies the incompressible condition automatically.

Let \mathcal{D} be an interval (or a domain) in R^1 (or R^2). $L^2(\mathcal{D})$, $H^r(\mathcal{D})$ and $H_0^r(\mathcal{D})$ ($r > 0$) denote the usual Hilbert spaces with the usual inner products and norms. We also define

$$L_0^2(\mathcal{D}) = \{\eta \in L^2(\mathcal{D}) / \int_{\mathcal{D}} \eta \, d\mathcal{D} = 0\}.$$

Let $\omega(x) = (1 - x^2)^{-\frac{1}{2}}$ and

$$(u, v)_{\omega, I_x} = \int_{I_x} uv\omega \, dx, \quad \|v\|_{\omega, I_x} = (v, v)_{\omega, I_x}^{\frac{1}{2}},$$

$$L_{\omega}^2(I_x) = \{v / v \text{ is measurable and } \|v\|_{\omega, I_x} < \infty\}.$$

Furthermore

$$(u, v)_{\omega} = \int \int_{\Omega} uv\omega \, dx dy, \quad \|v\|_{\omega} = (v, v)_{\omega}^{\frac{1}{2}},$$

$$L_{\omega}^2(\Omega) = \{v / v \text{ is measurable and } \|v\|_{\omega} < \infty\}.$$

Now we construct the scheme. For any positive integer N , we denote by \mathcal{P}_N the set of all polynomials of degree $\leq N$, defined on R^1 . Let

$$V_N(I_x) = \{v(x) \in \mathcal{P}_N / v(-1) = v(1) = 0\},$$

$$W_N(I_x) = \{v(x) \in \mathcal{P}_N / \frac{dv}{dx}(-1) = \frac{dv}{dx}(1) = 0\}.$$

Next, we divide I_y into M_h subintervals with the nodes $0 = y_0 < y_1 < \dots < y_{M_h} = 1$. Let $I_l = (y_{l-1}, y_l)$, $h_l = y_l - y_{l-1}$, $h = \max_{1 \leq l \leq M_h} h_l$ and $h' = \min_{1 \leq l \leq M_h} h_l$. Assume that there exists a positive constant d independent of the divisions of I_y , such that $h/h' \leq d$. Let

$$\tilde{S}_h^k(I_y) = \{v(y) / v(y) |_{I_l} \in \mathcal{P}_k, 1 \leq l \leq M_h\}, \quad S_h^k(I_y) = \tilde{S}_h^k(I_y) \cap H_0^1(I_y).$$

The trial function space $X_{N,h}^k(\Omega)$ for the speed and the trial function space $Y_{N,h}^k(\Omega)$ for the pressure are defined by

$$X_{N,h}^k(\Omega) = V_N(I_x) \otimes S_h^k(I_y), \quad Y_{N,h}^k(\Omega) = \{W_N(I_x) \otimes (\tilde{S}_h^k(I_y) \cap H^1(I_y))\} \cap L_0^2(\Omega).$$

In addition, let

$$Z_{N,h}^k(\Omega) = \{\mathcal{P}_{N-2}(I_x) \otimes (\tilde{S}_h^k(I_y) \cap H^1(I_y))\} \cap L_0^2(\Omega).$$

We denote by P_N^0 the $L_{\omega}^2(I_x)$ -orthogonal projection from $L_{\omega}^2(I_x)$ onto $V_N(I_x)$, Π_h^k is the piecewise Lagrange interpolation of order $k \geq 1$, from $C(\bar{I}_y)$ onto $\tilde{S}_h^k(I_y) \cap H^1(I_y)$. Furthermore let $P_{N,h} : L_{\omega}^2(\Omega) \rightarrow X_{N,h}^k(\Omega)$ be the orthogonal projection, i.e., for any $v \in L_{\omega}^2(\Omega)$, the projection $P_{N,h}v \in X_{N,h}^k(\Omega)$ and

$$(v - P_{N,h}v, u)_{\omega} = 0, \quad \forall u \in X_{N,h}^k(\Omega).$$

Let τ be the mesh size in time t and $S_{\tau} = \{t = l\tau / 0 \leq l \leq [\frac{T}{\tau}]\}$. Let

$$u_t(t) = \frac{1}{\tau}(u(t + \tau) - u(t)).$$