

KAM Theory for Partial Differential Equations

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Abstract. In the last years much progress has been achieved in KAM theory concerning bifurcation of quasi-periodic solutions of Hamiltonian or reversible partial differential equations. We provide an overview of the state of the art in this field.

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1 Introduction

Many partial differential equations (PDEs) arising in Physics are infinite dimensional dynamical systems

$$u_t = X(u), \quad u \in E, \quad (1.1)$$

defined on an infinite dimensional phase space E of functions $u := u(x)$, whose vector field X (in general unbounded) is Hamiltonian or Reversible. A vector field X is Hamiltonian if

$$X(u) = J\nabla H(u),$$

where J is a non-degenerate antisymmetric linear operator, the function $H : E \rightarrow \mathbb{R}$ is the Hamiltonian and ∇ denotes the L^2 -gradient. We refer to [106] for a general introduction to Hamiltonian PDEs. A vector field X is reversible if there exists an involution S of the phase space, i.e., a linear operator of E satisfying $S^2 = \text{Id}$, see e.g., (1.21), such that

$$X \circ S = -S \circ X.$$

Such symmetries have important consequences on the dynamics of (1.1), as we describe below. Classical examples are

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1. Nonlinear wave (NLW)/ Klein-Gordon.

$$y_{tt} - \Delta y + V(x)y = f(x, y), \quad x \in \mathbb{T}^d := (\mathbb{R}/2\pi\mathbb{Z})^d, \quad y \in \mathbb{R}, \quad (1.2)$$

with a real valued potential $V(x) \in \mathbb{R}$. If $V(x) = m$ is constant, (1.2) is also called a nonlinear Klein-Gordon equation. Eq. (1.2) can be written as the first order Hamiltonian system

$$\frac{d}{dt} \begin{pmatrix} y \\ p \end{pmatrix} = \begin{pmatrix} p \\ \Delta y - V(x)y + f(x, y) \end{pmatrix} = \begin{pmatrix} 0 & \text{Id} \\ -\text{Id} & 0 \end{pmatrix} \begin{pmatrix} \nabla_y H(y, p) \\ \nabla_p H(y, p) \end{pmatrix},$$

where $\nabla_y H, \nabla_p H$ denote the $L^2(\mathbb{T}_x^d)$ -gradient of the Hamiltonian

$$H(y, p) := \int_{\mathbb{T}^d} \frac{p^2}{2} + \frac{1}{2} ((\nabla_x y)^2 + V(x)y^2) + F(x, y) dx \quad (1.3)$$

with potential $F(x, y) := -\int_0^y f(x, z) dz$ and $\nabla_x y := (\partial_{x_1} y, \dots, \partial_{x_d} y)$.

Considering in (1.3) an Hamiltonian density $F(x, y, \nabla_x y)$, which depends also on the first order derivatives $\nabla_x y$, the corresponding Hamiltonian PDE is a quasi-linear wave equation with a nonlinearity which depends (linearly) with respect to the second order derivatives $\partial_{x_i x_j}^2 y$.

If the nonlinearity $f(x, y, \nabla_x y)$ in (1.2) depends on first order derivatives, the equation, called derivative nonlinear wave equation (DNLW), is no more Hamiltonian (at least with the usual symplectic structure) but it can admit a reversible symmetry, see e.g., [20].

2. Nonlinear Schrödinger (NLS).

$$iu_t - \Delta u + V(x)u = \partial_{\bar{u}} F(x, u), \quad x \in \mathbb{T}^d, \quad u \in \mathbb{C}, \quad (1.4)$$

where $F(x, u) \in \mathbb{R}$, $\forall u \in \mathbb{C}$, and, for $u = a + ib$, $a, b \in \mathbb{R}$, we define the operator $\partial_{\bar{u}} := \frac{1}{2}(\partial_a + i\partial_b)$. The NLS equation (1.4) can be written as the infinite dimensional complex Hamiltonian equation

$$u_t = i\nabla_{\bar{u}} H(u), \quad H(u) := \int_{\mathbb{T}^d} |\nabla u|^2 + V(x)|u|^2 - F(x, u) dx.$$

A simpler pseudo-differential model equation which is often considered is (1.4) with the multiplicative potential replaced by a convolution potential $V * u$, defined as the Fourier multiplier

$$u(x) = \sum_{j \in \mathbb{Z}^d} u_j e^{ij \cdot x} \mapsto V * u := \sum_{j \in \mathbb{Z}^d} V_j u_j e^{ij \cdot x}.$$

If the nonlinearity in the right hand side in (1.4) depends also on first and second order derivatives, we have, respectively, derivative NLS (DNLS) and fully-non-linear (or quasi-linear) Schrödinger type equations. According to the nonlinearity it may admit an Hamiltonian or reversible structure.