DOI: 10.4208/ata.2015.v31.n1.5

Analysis in Theory and Applications Anal. Theory Appl., Vol. **31**, No. 1 (2015), pp. 58-67

## *C<sup>p</sup>* Condition and the Best Local Approximation

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Received 22 May 2014; Accepted (in revised version) 8 March 2015

**Abstract.** In this paper, we introduce a condition weaker than the  $L^p$  differentiability, which we call  $C^p$  condition. We prove that if a function satisfies this condition at a point, then there exists the best local approximation at that point. We also give a necessary and sufficient condition for that a function be  $L^p$  differentiable. In addition, we study the convexity of the set of cluster points of the net of best appoximations of f,  $\{P_{\epsilon}(f)\}$  as  $\epsilon \to 0$ .

**Key Words**: Best *L<sup>p</sup>* approximation, local approximation, *L<sup>p</sup>* differentiability.

AMS Subject Classifications: 41A50, 41A10

## 1 Introduction

Let  $x_1$ ,  $a \in \mathbb{R}$ , a > 0, and let  $\mathcal{L}$  be the space of equivalence class of Lebesgue measurable real functions defined on  $I_a := (x_1 - a, x_1 + a)$ . For each Lebesgue measurable set  $A \subset I_a$ , with |A| > 0, we consider the semi-norm on  $\mathcal{L}$ ,

$$\|h\|_{p,A} := \left(|A|^{-1} \int_{A} |h(x)|^{p} dx\right)^{1/p}, \quad 1$$

where |A| denotes the measure of the set A. As usual, we denote by  $L^p(I_a)$  the space of functions  $h \in \mathcal{L}$  with  $||h||_{p,I_a} < \infty$ . If  $0 < \epsilon \le a$ ,  $I_{-\epsilon} := (x_1 - \epsilon, x_1)$ ,  $I_{+\epsilon} := (x_1, x_1 + \epsilon)$ , we write  $||h||_{p, I_{\epsilon}} = ||h||_{p, I_{\epsilon}}$ , and  $||h||_{p,\epsilon} = ||h||_{p,I_{\epsilon}}$ . For a non negative integer s, we denote by  $\Pi^s$  the linear space of polynomials of degree at most s. Henceforward, we consider  $n \in \mathbb{N} \cup \{0\}$ . If  $h \in L^p(I_a)$ , it is well known that there exists a unique best  $||\cdot||_{p,\epsilon}$ -approximation of h from  $\Pi^n$ , say  $P_{\epsilon}(h)$ , i.e.,  $P_{\epsilon}(h) \in \Pi^n$  satisfies

$$||h-P_{\epsilon}(h)||_{p,\epsilon} \leq ||h-P||_{p,\epsilon}$$
 for all  $P \in \Pi^n$ .

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 $P_{\epsilon}(h)$  is the unique polynomial in  $\Pi^{n}$ , which verifies

$$\int_{I_{\epsilon}} |(h - P_{\epsilon}(h))(x)|^{p-1} \operatorname{sgn}((h - P_{\epsilon}(h))(x))(x - x_1)^j dx = 0, \quad 0 \le j \le n,$$
(1.1)

see [2].

If  $\lim_{\epsilon \to 0} P_{\epsilon}(h)$  exists, say  $P_0(h)$ , it is called the *best local approximation of h at x*<sub>1</sub> *from*  $\Pi^n$  (b.l.a.). In general, we shall also denote by  $P_0(h)$  the set

$$\Big\{P\in\Pi^n:P=\lim_{k\to\infty}P_{\epsilon_k}(h) \text{ for some } \epsilon_k\downarrow 0\Big\}.$$

The problem of best local approximation was formally introduced and studied in a paper by Chui, Shisha and Smith [3]. However, the initiation of this could be dated back to results of J. L. Walsh [10], who proved that the Taylor polynomial of an analytic function h over a domain is the limit of the net of polynomial best approximations of a given degree, by shrinking the domain to a single point. Later, several authors studied the existence of the b.l.a. assuming a certain order of differentiability. In [8] and [12], this problem was considered when h is  $L^p$  differentiable. Recently, in [7] and [5] the authors proved the existence of the b.l.a. under weaker conditions, more precisely they assumed existence of lateral  $L^p$  derivatives of order n and  $L^p$  differentiability of order n-1. In [4] it was proved that if p = 2 and h is differentiable up to order n-1, then  $P_0(h)$  is either empty or convex. Later, in [11] using interpolation properties of the best approximation, the author extended this result for 1 . The main purpose of this paper is to givemore general conditions on a function <math>h so that there exists the b.l.a., and to study its connection with the  $L^p$  differentiability. Further, we study the convexity of  $P_0(h)$ . The following definition is motivated by the characterization (1.1).

**Definition 1.1.** We shall say that  $f \in L^p(I_a)$  satisfies the  $C^p$  condition of order n at  $x_1$ , if there exists  $Q \in \Pi^n$  such that

$$\int_{I_{\epsilon}} |(f-Q)(x)|^{p-1} \operatorname{sgn}((f-Q)(x))(x-x_1)^j dx = o(\epsilon^{n(p-1)+j+1}),$$
(1.2)

 $0 \le j \le n$ , as  $\epsilon \to 0$ .

Analogously, we shall say that *f* satisfies the left (right)  $C^p$  condition of order *n* at  $x_1$ , if there exists  $Q \in \Pi^n$  verifying (1.2) with  $I_{-\epsilon}(I_{+\epsilon})$  instead of  $I_{\epsilon}$ .

We denote with  $c_n^p(x_1)$  the class of functions in  $L^p(I_a)$  which satisfy the  $C^p$  condition of order n at  $x_1$ . We recall that a function  $f \in L^p(I_a)$  is  $L^p$  differentiable of order n at  $x_1$  (i.e.,  $f \in t_n^p(x_1)$ ) if there exists  $Q \in \Pi^n$  such that  $||f - Q||_{p,\epsilon} = o(\epsilon^n)$ . This concept was introduced by Calderón and Zygmund in [1]. Using the Hölder inequality, it is easy to see that  $t_n^p(x_1) \subset c_n^p(x_1)$ , moreover the inclusion is strict. In fact, if  $h(x) = \sin(1/x)$ ,  $x \neq 0$ , then  $h \in c_0^2(0)$ , however a straightforward computation shows that  $h \notin t_0^2(0)$ . It immediately follows from Definition 1.1 that  $c_n^p(x_1)$  satisfies: a) If  $f \in c_n^p(x_1)$ , then  $f + P \in c_n^p(x_1)$  for