Generalized Inverse Analysis on the Domain $\Omega(A, A^+)$ **in** B(E, F)

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Received 4 September 2017; Accepted (in revised version) 8 November 2017

Abstract. Let B(E,F) be the set of all bounded linear operators from a Banach space E into another Banach space $F, B^+(E,F)$ the set of all double splitting operators in B(E,F) and GI(A) the set of generalized inverses of $A \in B^+(E,F)$. In this paper we introduce an unbounded domain $\Omega(A,A^+)$ in B(E,F) for $A \in B^+(E,F)$ and $A^+ \in GI(A)$, and provide a necessary and sufficient condition for $T \in \Omega(A,A^+)$. Then several conditions equivalent to the following property are proved: $B = A^+(I_F + (T - A)A^+)^{-1}$ is the generalized inverse of T with $R(B) = R(A^+)$ and $N(B) = N(A^+)$, for $T \in \Omega(A,A^+)$, where I_F is the identity on F. Also we obtain the smooth (C^{∞}) diffeomorphism $M_A(A^+,T)$ from $\Omega(A,A^+)$ onto itself with the fixed point A. Let $S = \{T \in \Omega(A,A^+) : R(T) \cap N(A^+) = \{0\}\}$, $M(X) = \{T \in B(E,F) : TN(X) \subset R(X)\}$ for $X \in B(E,F)\}$, and $\mathcal{F} = \{M(X) : \forall X \in B(E,F)\}$. Using the diffeomorphism $M_A(A^+,T)$ we prove the following theorem: S is a smooth submanifold in B(E,F) and tangent to M(X) at any $X \in S$. The theorem expands the smooth integrability of \mathcal{F} at A from a local neighborhoold at A to the global unbounded domain $\Omega(A,A^+)$. It seems to be useful for developing global analysis and geomatrical method in differential equations.

Key Words: Generalized inverse analysis, smooth diffeomorphism, smooth submanifold.

AMS Subject Classifications: 47B38, 15A29, 58A05

1 Introduction

Let *E*, *F* be two Banach spaces, B(E,F) the set of all linear bounded operators from *E* into $F,B^+(E,F)$ that of all double splitting operators in B(E,F), and GI(A) that of all generalized inverses of *A* for $A \in B^+(E,F)$. Write $V(A,A^+) = \{T \in B(E,F) : ||T-A|| < ||A^+||^{-1}\}$ for $A \in B^+(E,F)$ and $A^+ \in GI(A), C_A(A^+,T) = I_F + (T-A)A^+$ and $D_A(A^+,T) = I_E + A^+(T-A)$, where I_E and I_F denote the identities on *F* and *E*, respectivelly. In 1993, Nashed M. Z. and Chen X. indicated in [1] that if $C^+_A(A^+,T)R(T) \subset R(A)$ for $T \in V(A,A^+)$, then the

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following property holds: $B = A^+C_A^{-1}(A^+,T) = D_A^{-1}(A^+,T)$ is the generalized inverse of *T* with $R(B) = R(A^+)$ and $N(B) = N(A^+)$. This property is essential to the theory of generalized inverse analysis. Then sevaral conditions equivalent to the property are presented (for details see [2–5]). Let T_x be an operator valued map from a topological spaces X into B(E,F). Especially in 1999, the concept of locally fine point of T_x is introduced, see [2]. Thanks to it the complete rank theorem in advanced calculus and the operator rank theorem both are established, see [2,3]. The previous one gives a complete answer to the rank theorem problem presented by Beger M. S in [6], and the latter expands Penrose theorem from the case of matrices to that of operators (see [3,7] and [5]). Many applications of them are given in [5, 8, 9] and [10]. So far we may say that the generalized inverse analysis is built. In this paper we introduce the unbouded domain $\Omega(A, A^+)$ in B(E, F) for $A \in B^+(E, F)$ and $A^+ \in GI(A)$, and show a necessary and sufficient condition for $T \in \Omega(A, A^+)$. Moreover, several conditions equivalent to the above property for $T \in \Omega(A, A^+)$ are given in Theorem 3.1 in the next Section 3. Also we obtain a smooth diffeomorphism from $\Omega(A, A^+)$ onto itself with a fixed point A, i.e., Theorem 4.1 in Section 4 holds. Let $S = \{T \in \Omega(A, A^+) : R(T) \cap N(A^+) = \{0\}\}$ for any $A \in B^+(E, F)$ and $A^+ \in GI(A), M(X) = \{T \in B(E,F): TN(X) \subset R(X)\}$, and $\mathcal{F} = \{M(X): \forall X \in B(E,F)\}$. Using this smooth diffeomorphism we prove that S is a smooth submanifold in B(E,F) and tangent to M(X) at any $X \in S$, i.e., Theorem 4.2 in the next Section 4 holds. The theorem expands the smooth integrability of \mathcal{F} at A as indecated in Theorem 4.1 in [6] from a local neighborhood at *A* to the global unbounded domain $\Omega(A, A^+)$. These seem to be useful for developing the global analysis and geomatrical method in differential equations.

2 The domain $\Omega(A, A^+)$ in B(E, F)

Let B(F) = B(F,F) and $B^X(F)$ be the set of all invertible operators in B(F). Write $C_A(A^+,T) = I_F + (T-A)A^{-1} \in B(F)$ for $A \in B^+(E,F)$ and $A^+ \in GI(A)$, where I_F denotes the identity on F. We define

$$\Omega(A, A^+) = \{T \in B(E, F) : C_A(A^+, T) \in B^X(F)\}$$

for $A \in B^+(E,F)$ and $A^+ \in GI(A)$. For abbreviation, write $P_{R(A^+)}^{N(A)}$, $P_{N(A)}^{R(A^+)}$, $P_{R(A)}^{N(A^+)}$ and $P_{N(A^+)}^{R(A)}$ as $P_{R(A^+)}$, $P_{N(A)}$, $P_{R(A)}$ and $P_{N(A^+)}$, respectively, in the sequel. Then $C_A(A^+,T) = P_{N(A^+)} + TA^{-1}$. We have

Theorem 2.1. *T* belongs to $\Omega(A, A^+)$ if and only if the following conditions hold:

$$N(T) \cap R(A^+) = \{0\}$$

and

$$F = R(TA^+) \oplus N(A^+). \tag{2.1}$$